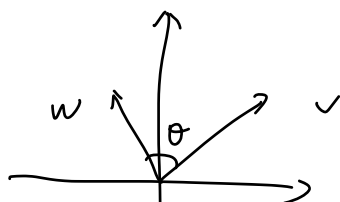


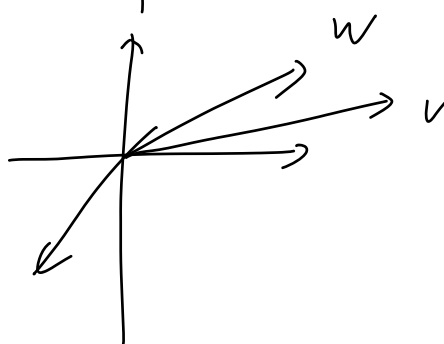
\mathbb{R}^n 更多结构

\mathbb{R}^2



长度, 角度

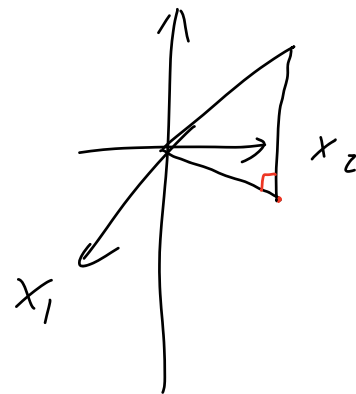
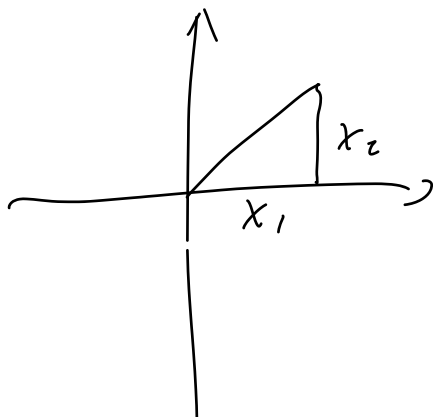
\mathbb{R}^3



内积, 点积
inner product
dot product.

定义: $x = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} \in \mathbb{R}^n$. 长度

$$|x| = \sqrt{(x_1)^2 + (x_2)^2 + \dots + (x_n)^2}$$



定义: $q(x) = |x|^2 = x_1^2 + x_2^2 + \dots + x_n^2$

定义：内积 $g: \mathbb{R}^n \times \mathbb{R}^n \rightarrow \mathbb{R}$
 $(x, y) \mapsto g(x, y)$

$$x = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}, y = \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix} \quad = \sum_{i=1}^n x_i y_i \\ = x^T y$$

记号 $\langle x, y \rangle = g(x, y) = x^T y$.

$q(x) = g(x, x)$

性质：① $\langle \cdot, \cdot \rangle$ 双线性 \checkmark

$$\forall c \in \mathbb{R}, x, y, z \in \mathbb{R}^n$$

$$\langle x, y+z \rangle = \langle x, y \rangle + \langle x, z \rangle$$

$$\langle x, c \cdot y \rangle = c \cdot \langle x, y \rangle$$

$$\langle x+y, z \rangle = \langle x, z \rangle + \langle y, z \rangle$$

$$\langle c x, y \rangle = c \cdot \langle x, y \rangle$$

② 对称性. $\langle x, y \rangle = \langle y, x \rangle \checkmark$

③ $q(x) = \langle x, x \rangle \geq 0$ (正定性) \checkmark

$$q(x) = 0 \Leftrightarrow x = 0$$

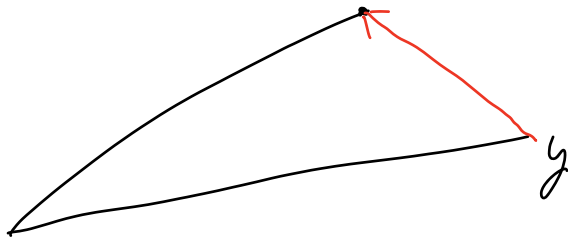
④ $\langle x, y \rangle = \frac{1}{2} (q(x+y) - q(x) - q(y))$

验证.

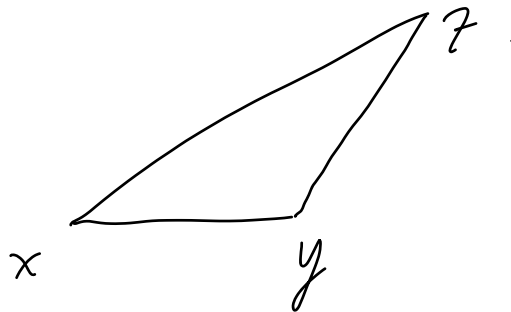
④ \Rightarrow “保持长度” \Rightarrow “保持内积”.

定义: \mathbb{R}^n 中两点之间的距离

$$\text{dist}(x, y) \stackrel{\text{定义}}{=} \sqrt{q(x-y)} \geq 0$$



距离不等式 (三角不等式)



$$\begin{aligned} & \text{dist}(x, y) \\ & + \text{dist}(y, z) \\ & \geq \text{dist}(x, z) \end{aligned}$$

证明: $\sqrt{q(x-y)} + \sqrt{q(y-z)} \geq \sqrt{q(x-z)}$

$$\Leftrightarrow \sqrt{q(x)} + \sqrt{q(y)} \geq \sqrt{q(x+y)}$$

$$\text{平方 } (\Rightarrow) \quad q(x) + q(y) + \underline{2\sqrt{q(x)q(y)}} \\ \geq \underline{q(x+y)}$$

$$(\Rightarrow) \quad |\langle x, y \rangle|^2 \leq \langle x, x \rangle \cdot \langle y, y \rangle$$

性质: (柯西不等式)

Pf: $q(x+ty) \geq 0, \quad \forall t \in \mathbb{R}$

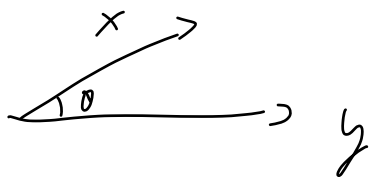
$$t^2 \langle y, y \rangle + 2t \langle x, y \rangle + \langle x, x \rangle \geq 0$$

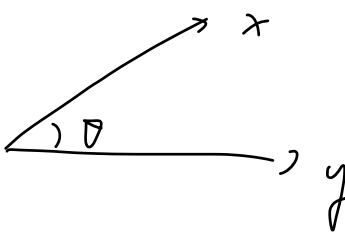
判别式 $\Delta \leq 0$

\Rightarrow Cauchy 不等式.

例题: $\mathbb{R}^2, \mathbb{R}^3$

几何: $\langle x, y \rangle = |x| \cdot |y| \cdot \cos \theta$



定义：
(为什么?)  夹角 θ . 定义为

$$\underline{\langle x, y \rangle = |x| \cdot |y| \cdot \cos \theta.}$$

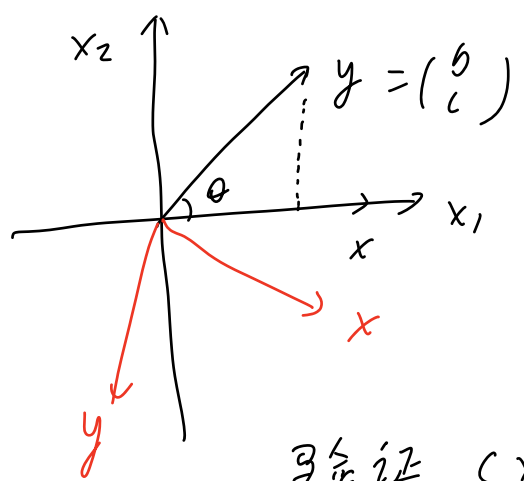
由 Cauchy, $x \neq 0, y \neq 0,$

$$\underline{-1 \leq \frac{\langle x, y \rangle}{|x| |y|} \leq 1}$$

$x = 0$, 或 $y = 0$, θ 任意值.

定义: 正交 (垂直) $x \perp y$. x 与 y 正交
定义为 $\langle x, y \rangle = 0$

特殊情况: \mathbb{R}^2 $x = \begin{pmatrix} a \\ 0 \end{pmatrix}, y = \begin{pmatrix} b \\ c \end{pmatrix}$



$$\langle x, y \rangle = ab$$

$$b = |y| \cdot \cos \theta$$

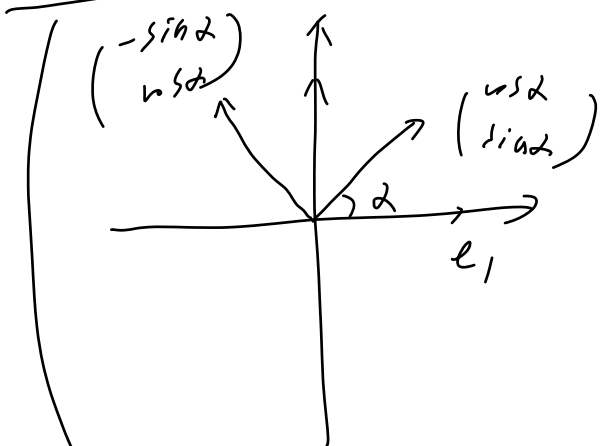
$$\underline{0 \leq \theta \leq \frac{\pi}{2}}$$

验证 $\langle x, y \rangle = |x| \cdot |y| \cdot \cos \theta.$

一般 $x, y \in \mathbb{R}^2$, 通过“旋转”将 x, y 移动到特殊位置.

"旋转" 不改变角度 (几何上)

验证 旋转 不改变内积. (代数上)



逆时针旋转 α

$$A = \begin{bmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{bmatrix}$$

$$\langle Ax, Ay \rangle = \langle x, y \rangle$$

$$\Leftrightarrow (Ax)^T Ay = x^T y.$$

$$\Leftrightarrow x^T (A^T A) y = x^T y.$$

$$\begin{aligned} \underline{A^T A} &= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} \cos \alpha & \sin \alpha \\ -\sin \alpha & \cos \alpha \end{bmatrix} \cdot \begin{bmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{bmatrix} \\ &= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \end{aligned}$$

定义 (正交矩阵) $A \in M_n(\mathbb{R})$

$$A^T A = \underline{I} \quad \left(\begin{array}{l} (\Leftrightarrow) A^T = A^{-1} \\ (\Leftrightarrow) A \cdot A^T = I \end{array} \right)$$

正交矩阵的集合 $O(n) = \{ A \in M_n(\mathbb{R})$

(可替换成 $q(Ax) = q(x), \forall x \in \mathbb{R}^n$) $A^T A = \underline{I}$

性质: $\forall x, y \in \mathbb{R}^n, \langle Ax, Ay \rangle = \langle x, y \rangle$
当且仅当 $A \in O(n)$

Pf: "当" $\langle Ax, Ay \rangle = x^T (A^T A) y$
 $= x^T y$
 $= \langle x, y \rangle$

"仅当": $\langle Ax, Ay \rangle = x^T (A^T A) y$

取 $x = e_i = \begin{pmatrix} 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{pmatrix}$ \leftarrow i 行 = 1

$y = e_j$

$x^T \cdot (A^T A) \cdot y = A^T A$ i 行 j 列元素

$$e_i^T \cdot e_j = \delta_{ij} = \begin{cases} 1 & i=j \\ 0 & i \neq j \end{cases}$$

$$\Rightarrow A^T A = I_n$$

线性变换角度:

定义: (正交变换) $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$

$$\langle T(v), T(w) \rangle = \langle v, w \rangle, \quad \forall v, w \in \mathbb{R}^n$$

性质: T 是正交变换 当且仅当

T 在标准基 $B: e_1, \dots, e_n$ 下

$$[T]_B^B \in O(n)$$

T 在基上的作用决定了 T .

$$\begin{array}{ccc} T(e_1) & \dots & T(e_n) \\ \parallel & & \parallel \\ v_1 & & v_n \end{array}, \quad [T]_B^B = A = [v_1, \dots, v_n]$$

找到 $A \in O(n)$ 关于 v_1, \dots, v_n 的关系

$$A^T A = \begin{pmatrix} v_1^T \\ \vdots \\ v_h^T \end{pmatrix} \cdot (v_1 \cdots v_n)$$

$$= \left(v_i^T \cdot v_j \right)_{\substack{1 \leq i \leq n \\ 1 \leq j \leq n}}$$

$$= \left(\langle v_i, v_j \rangle \right)$$

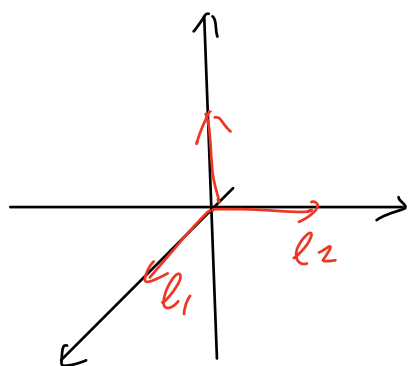
$$A \in O(n) \Leftrightarrow (*) \langle v_i, v_j \rangle = \delta_{ij} = \begin{cases} 1 & i=j \\ 0 & i \neq j \end{cases}$$

定义: 基 v_1, \dots, v_n 满足 (*), 称 v_1, \dots, v_n 标准正交基.

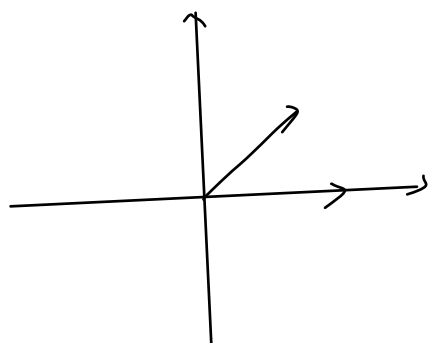
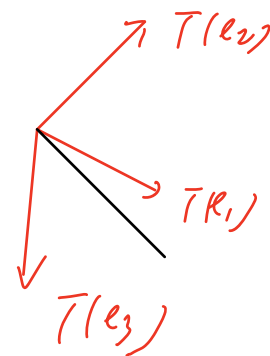
(性质: $v_1, \dots, v_n, v_i \neq 0, \langle v_i, v_j \rangle = 0, i \neq j, \Rightarrow v_1, \dots, v_n$ 线性无关)

性质: $A \in O(n), \Leftrightarrow v_1, \dots, v_n$ 是标准正交基.

性质': T 正交变换 $\Leftrightarrow T$ 将标准正交基 变为标准正交基



T

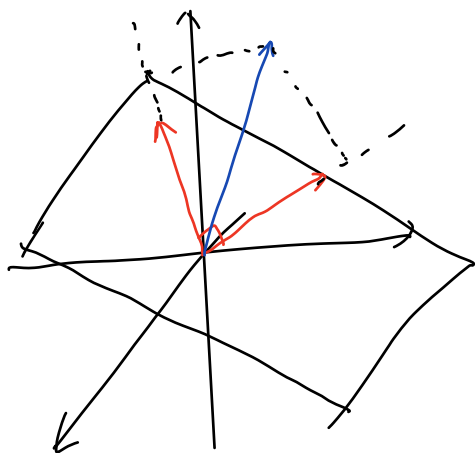


B 是标准正交基
 $|v|^2 = [v]_B$ 各分量平方和.

对 $W \subset \mathbb{R}^n$ 子空间, 可定义标准正交基

$B: w_1, \dots, w_n$ W 基

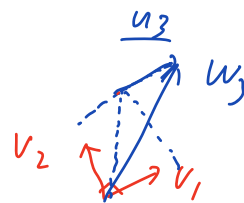
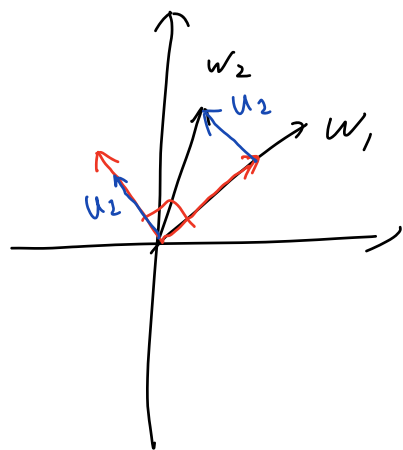
满足 $\langle w_i, w_j \rangle = \delta_{ij}$



存在性: (Gram-Schmidt 正交化)

w_1, \dots, w_m linearly independent $W = \text{Span}(w_1, \dots, w_m)$

(G-S) \Rightarrow 生成 W 的标准正交基.



$$\begin{cases} u_1 = w_1, & v_1 = \frac{u_1}{|u_1|}, & \langle v_1, v_1 \rangle = 1 \\ u_2 = w_2 + c v_1 = w_2 - \langle w_2, v_1 \rangle v_1, & v_2 = \frac{u_2}{|u_2|}, \end{cases}$$

(c 使得 $\langle u_2, v_1 \rangle = 0$.

$$\langle w_2 + c v_1, v_1 \rangle = 0$$

$$\langle w_2, v_1 \rangle + c \langle v_1, v_1 \rangle = 0$$

$$c = - \langle w_2, v_1 \rangle$$

$$\langle v_2, v_1 \rangle = 0$$

$$\langle v_2, v_2 \rangle = 1$$

$$u_3 = w_3 - \langle w_3, v_2 \rangle v_2 - \langle w_3, v_1 \rangle v_1.$$

验证 $\langle u_3, v_2 \rangle = 0, \quad \langle u_3, v_1 \rangle = 0.$

$$v_3 = \frac{u_3}{|u_3|}, \quad \begin{aligned} \langle v_3, v_2 \rangle &= 0 \\ \langle v_3, v_1 \rangle &= 0 \\ \langle v_3, v_3 \rangle &= 1 \end{aligned}$$

$u_m,$

$v_m.$

$(v_1 \dots v_m)$ 是标准正交基.

$$\underline{(w_1 \dots w_m)} = \underline{(v_1 \dots v_m)} \begin{pmatrix} \langle w_1, v_1 \rangle, \langle w_2, v_1 \rangle \\ 0 & \dots, \langle w_2, v_2 \rangle \\ \vdots & \vdots \\ 0 & \dots, 0 \end{pmatrix}$$

↑
上三角阵

推论: 任一标准正交向量组可扩充标准正交基.

$w_1 \dots w_m$ $v_{m+1} \dots v_n$ 扩充为基.

$$\begin{pmatrix} \cup \\ \cap \end{pmatrix} w_1 \dots w_m \quad v'_{m+1} \dots v'_n$$

(非线性相关, GS 类似)

$m \geq n$

"长矩阵". $M \in M_{m \times n}(\mathbb{R})$. $\text{rk}(M) = n$.

$$M = \begin{pmatrix} w_1 & \cdots & w_n \end{pmatrix} \quad \frac{w_i \in \mathbb{R}^m}{}$$

$$M = \underbrace{(v_1 \cdots v_n)}_{\substack{Q_1 \\ m \times n}} \cdot \begin{bmatrix} \diagup \\ 0 \end{bmatrix} \leftarrow \text{上三角阵.}$$

$$= Q_1 \cdot R_1$$

$$Q_1 \quad m \times n.$$

$$R_1 \quad \underline{n \times n \text{ 上三角.}}$$

$$= Q \cdot R$$

$$Q = (Q_1, Q_2)$$

$$\in O(m)$$

称为 QR 分解.

$m = n$ 时, A 可逆

$$R = \begin{pmatrix} R_1 \\ 0 \end{pmatrix}$$

$$m \times n$$

$$A = \underbrace{Q}_{\substack{\downarrow \\ \text{正交}}} \underbrace{R}_{\substack{\downarrow \\ \text{上三角阵. (对角线} > 0 \text{)}}}$$

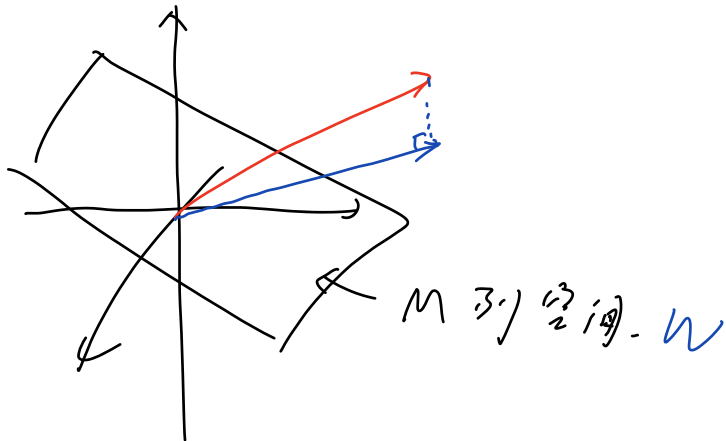
(唯一性)

求解 $\underline{M \cdot x = b}$, $M \in \mathbb{R}^{m \times n}$,
 $b \in \mathbb{R}^m$.

$\text{rk } M = n$

$\underline{m \geq n}$.

不一定有解.



找近似解: $|M \cdot x - b|$ 最小.

$\Leftrightarrow Mx - b \perp W$

$$M = Q \cdot R = (a_1 \ a_2) \cdot \begin{pmatrix} R_1 \\ 0 \end{pmatrix}$$

$$\begin{aligned} |Mx - b|^2 &= |QRx - b|^2 \\ &= |Rx - Q^T b|^2 \end{aligned}$$

$$R_1 = \begin{bmatrix} * & & * \\ & \ddots & \\ 0 & & * \end{bmatrix}$$

$$= \left| \begin{pmatrix} R_1 \cdot x \\ 0 \end{pmatrix} - \begin{pmatrix} C_1 \\ C_2 \end{pmatrix} \right|^2$$

$$= \underbrace{|R_1 \cdot x - C_1|^2}_{0''} + \underbrace{|C_2|^2}$$

$$\boxed{R_1 \cdot x = C_1}$$